## UNSW MATHEMATICS SOCIETY PRESENTS MATH2089/2099/2859



## **CVEN2002** Revision Seminar

Statistics

T2, 2020

## Table of Contents I

- **1** Part I: Random variables
  - Cumulative distribution function
  - Discrete RVs
  - Continuous RVs
  - Expectation
  - Variance and standard deviation
  - Joint distributed RVs
    - Marginal functions
    - Independence of two random variables
  - Covariance and correlation

2 Part II: Sampling distributions and Central Limit Theorem

- Random sampling
- Central Limit Theorem
- Estimators

### **3** Part III: Confidence intervals

Presented by: Gerald Huang

## Table of Contents II

- Sample size determination
- Confidence interval for a proportion
- One-sided confidence intervals for a proportion

### Part IV: Hypothesis testing

- Student's t distribution
- Null and Alternative Hypotheses
- Rejection region

### 5 Part V: Analyses

- Regression Analysis
- Assumptions of linear regression
- Variance Analysis
- Fisher's *F*-distribution

## Part I: Random variables

Presented by: Gerald Huang



## **Random variable**

### **Definition I: Random variable**

## A random variable is a real-valued function defined over the sample space $X : S \to \mathbb{R}$ and $\omega \to X(\omega)$ .

## Cumulative distribution function (CDF)

### Definition: Cumulative distribution function

A cumulative distribution function of a random variable X is defined, for any real number x, as

$$F(x) = \mathbb{P}(X \leq x).$$

### Properties.

• For any real numbers  $a \leq b$ , we have

$$\mathbb{P}(a < X \leq b) = F(b) - F(a).$$

• It is **nondecreasing**. That is, if  $x_1 \le x_2$ , then  $F(x_1) \le F(x_2)$ .

• 
$$\lim_{x \to +\infty} F(x) = 1$$
 and  $\lim_{x \to -\infty} F(x) = 0$ .

## **Discrete Random Variables**

### **Definition: Discrete Random Variables**

A random variable is said to be discrete if it can only assume a finite (or at most countably infinite) number of values.

• Essentially we can count each event!

### Characterising a discrete random variable

Discrete random variables can be characterised by their **probability mass function** (pmf), defined by

$$p(x) = \mathbb{P}(X = x).$$

• The sum of ALL elements x in the event A is 1. That is,

$$\sum_{x \in A} p(x) = 1.$$

MATH2089/2859/2099/CVEN2002 Revision Seminar

Presented by: Gerald Huang

7 / 72

## **Continuous Random Variables**

### **Definition: Continuous Random Variables**

A random variable is said to be **continuous** if it is defined over an **uncountable** set of real numbers, usually an intervals.

### Characterising a continuous random variable

Continuous random variables can be characterised by their **probability density function** (pdf), defined by f(x).

• The integral over ALL elements x in the event space A is 1. That is,

$$\int_A f(x)\,dx=1.$$

### **Example**

To determine whether  $f(x) = e^{-x}$  for x > 0 is a density function, check whether

$$\int_0^\infty e^{-x}\,dx=1.$$

Presented by: Gerald Huang

## **Expectation of random variables**

### Expectation of a discrete random variable

The expectation (or mean) of a discrete random variable, denoted  $\mathbb{E}(X)$  or  $\mu$ , is defined by

$$\mu = \mathbb{E}(X) = \sum_{x \in A} x p(x).$$

### Expectation of a continuous random variable

The expectation (or mean) of a continuous random variable, denoted  $\mathbb{E}(X)$  or  $\mu$ , is defined by

$$\mu = \mathbb{E}(X) = \int_A xf(x)\,dx.$$

## Expectation of random variables (18S2)

### Example: (2018 Semester 2, Q3a)

Let X follow the Bernoulli distribution:

$$p(x) = egin{cases} 1-\pi, & ext{if } x=0 \ \pi, & ext{if } x=1 \end{cases}$$

where  $0 < \pi < 1$ . Show that  $\mathbb{E}(X) = \pi$ .

Since this is a **discrete** random variable, then the expected value is simply

$$\mathbb{E}(X) = \sum_{x \in X} x p(x) = 0 \times (1 - \pi) + 1 \times \pi = \pi.$$

### Properties of the expectation function

• Linearity: For any two constants a and b, we have

$$\mathbb{E}(aX+b)=a\cdot\mathbb{E}(X)+b.$$

#### • Degenerate: A random variable X is said to be degenerate if

$$\mathbb{E}(b) = b.$$

Presented by: Gerald Huang

### Example

If  $\mathbb{E}(X) = 2$ , then

$$\mathbb{E}(3X+4)=3 imes\mathbb{E}(X)+4=3 imes2+4=10.$$

### **Example**

If 
$$\mathbb{E}(3X+4) = 10$$
, then  $3\mathbb{E}(X) + 4 = 10 \implies \mathbb{E}(X) = 2$ .

Presented by: Gerald Huang

## Variance of a random variable

### Variance of a random variable

The **variance** of a random variable, denoted by Var(X) or  $\sigma^2$ , is defined by

$$\operatorname{Var}(X) = \mathbb{E}\left[(X-\mu)^2\right] = \mathbb{E}(X^2) - \mathbb{E}(X)^2.$$

#### Properties of the variance function

- For any random variable,  $Var(X) \ge 0$ .
- For any two constants a and b,  $Var(aX + b) = a^2 \cdot Var(X)$ .
- For any constant b, Var(b) = 0.

## **Computing the variance**

Variance of a discrete random variable The variance of a discrete random variable is defined by

$$\operatorname{Var}(X) = \sum_{x \in A} (x - \mu)^2 p(x) = \underbrace{\left(\sum_{x \in A} x^2 p(x)\right)}_{\mathbb{E}(X^2)} - \underbrace{\left(\sum_{x \in A} x p(x)\right)^2}_{\mathbb{E}(X)^2}$$

### Variance of a continuous random variable

The variance of a continuous random variable is defined by

$$\operatorname{Var}(X) = \int_{\mathcal{A}} (x - \mu)^2 f(x) \, dx = \underbrace{\left(\int_{\mathcal{A}} x^2 f(x) \, dx\right)}_{\mathbb{E}(X^2)} - \underbrace{\left(\int_{\mathcal{A}} x f(x) \, dx\right)^2}_{\mathbb{E}(X)^2}$$

MATH2089/2859/2099/CVEN2002 Revision Semina

### Example

If  $f(x) = e^{-x}$  for x > 0, then the variance can be found by computing the integral

$$Var(X) = \mathbb{E}(X^{2}) - \mathbb{E}(X)^{2} = \int_{0}^{\infty} x^{2} e^{-x} dx - \left(\int_{0}^{\infty} x e^{-x} dx\right)^{2}$$

Presented by: Gerald Huang

MATH2089/2859/2099/CVEN2002 Revision Seminar

Part

## **Standard deviation**

• The **standard deviation** is simply the square root of the variance. That is,

$$SD(X) = \sqrt{Var(X)}.$$

 Since Var(X) ≥ 0, then the standard deviation function will always be defined!

## Jointly distributed random variables

• We will now turn towards the two-dimensional case and discuss properties of distributions of *two* random variables!

## Joint cumulative distribution function

**Definition:** Joint cumulative distribution function (discrete) The joint cumulative distribution function of discrete random variables X and Y is given by

 $F_{XY}(x,y) = \mathbb{P}(X \le x, Y \le y), \quad \text{for all } (x,y) \in \mathbb{R} \times \mathbb{R}.$ 

## Definition: Joint cumulative distribution function (continuous)

X and Y are said to be jointly continuous if, for any sets A and B of real numbers, there is a function (the joint probability density of X and Y)  $f_{XY}(x, y)$ 

$$\mathbb{P}(X \in A, Y \in B) = \int_A \int_B f_{XY}(x, y) \, dy \, dx.$$

## Joint distribution functions and marginal functions

### Discrete

Part I: Random variables

Joint distribution

$$p_{XY}(x,y) = \mathbb{P}(X = x, Y = y).$$

Marginal probabilities

$$p_X(x) = \sum_{y \in S_Y} p_{XY}(x, y).$$
$$p_Y(y) = \sum_{x \in S_X} p_{XY}(x, y).$$

### Continuous

Joint distribution

Denoted as  $f_{XY}(x, y)$ .

### Marginal densities

$$f_X(x) = \int_{S_Y} f_{XY}(x, y) \, dy.$$
  
$$f_Y(y) = \int_{S_X} f_{XY}(x, y) \, dx.$$

Presented by: Gerald Huang

20 / 72

## Expectation of a function of two random variables

For any function  $g: \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ , the expectation of g(X, Y) is given by

$$\mathbb{E}(g(X,Y)) =$$

Discrete random variables

**Continuous random variables** 

$$\sum_{x \in S_X} \sum_{y \in S_Y} g(x, y) p_{XY}(x, y)$$

$$\int_{S_X} \int_{S_Y} g(x, y) f_{XY}(x, y) \, dy \, dx$$

Linearity property of the expectation function still holds!

$$\mathbb{E}(aX + bY) = a \cdot \mathbb{E}(X) + b \cdot \mathbb{E}(Y).$$

### Example: Table of marginal probabilities

Assume that X is across the top and Y is on the side. Find  $\mathbb{P}(X \leq 1, Y \leq 1).$ 

$$\begin{split} \mathbb{P}(X \leq 1, Y \leq 1) \\ &= \mathbb{P}(X = 0, Y = -1) + \mathbb{P}(X = 0, Y = 1) \\ &+ \mathbb{P}(X = 1, Y = -1) + \mathbb{P}(X = 1, Y = 1) \\ &= 1/8 + 1/8 + 1/8 + 1/4 = 5/8. \end{split}$$

## Independent random variables

**Definition:** Independence of random variables Random variables X and Y are said to be **independent** if, for all  $(x, y) \in \mathbb{R} \times \mathbb{R}$ ,

$$\mathbb{P}(X \leq x, Y \leq y) = \mathbb{P}(X \leq x) \times \mathbb{P}(Y \leq y).$$

Discrete case

**Continuous case** 

$$p_{XY}(x,y) = p_X(x) \times p_Y(y).$$

$$f_{XY}(x,y) = f_X(x) \times f_Y(y).$$

**Property of independent random variables** If X and Y are **independent**, then for any functions h and g,

 $\mathbb{E}(h(X)g(Y)) = \mathbb{E}(h(X)) \times \mathbb{E}(g(Y)).$ 

Presented by: Gerald Huang

### Example: (MATH2089, 2009S1 Q5c)

Suppose that X and Y are independent standard normal variables. What is the distribution of X + Y?

Since X and Y are independently and normally distributed , then their sum is also normally distributed with

$$Z \sim \mathcal{N}(\mu_X + \mu_Y, \sigma_X^2, \sigma_Y^2) = \mathcal{N}(0, 2).$$

Presented by: Gerald Huang

## **Covariance of two random variables**

**Definition:** Covariance of two random variables The covariance of two random variables *X* and *Y* is defined as

$$Cov(X, Y) = \mathbb{E}\left[(X - \mathbb{E}(X))(Y - \mathbb{E}(Y))\right].$$

#### **Properties of covariance**

- Cov(X, X) = Var(X).
- Symmetric: For any two variables X and Y, Cov(X, Y) = Cov(Y, X).
- **IMPORTANT**:  $Cov(X, Y) = \mathbb{E}(XY) \mathbb{E}(X)\mathbb{E}(Y)$ .
- Cov(aX + b, cY + d) = ac Cov(X, Y)
- Bilinearity:  $Cov(X_1 + X_2, Y_1 + Y_2) = Cov(X_1, Y_1) + Cov(X_1, Y_2) + Cov(X_2, Y_1) + Cov(X_2, Y_2).$

## **Covariance and independence**

 If X and Y are independent, then Cov(X, Y) = 0. But if Cov(X, Y) = 0, then X and Y may or may not be independent!

### Remark

X and Y independent 
$$\implies$$
 Cov $(X, Y) = 0$ .  
Cov $(X, Y) = 0 \implies X$  and Y independent.

Presented by: Gerald Huang

## Variance of a sum of random variables

**Variance of a sum of two random variables** For any two random variables *X* and *Y*,

$$\operatorname{Var}(aX + bY) = a^2 \operatorname{Var}(X) + b^2 \operatorname{Var}(Y) + 2ab \operatorname{Cov}(X, Y)$$

• If X and Y are independent, then

$$\operatorname{Var}(aX + bY) = a^2 \operatorname{Var}(X) + b^2 \operatorname{Var}(Y).$$

Presented by: Gerald Huang

## **Correlation coefficient**

### **Definition:** Correlation

The correlation coefficient denoted by  $\rho$  is defined as

$$\rho = \frac{\operatorname{Cov}(X, Y)}{\sqrt{\operatorname{Var}(X)\operatorname{Var}(Y)}}.$$

• We are computing the covariance between the **standardised** versions of *X* and *Y*.

### **Properties of correlation**

- $\rho$  does not have a unit.
- $-1 \le \rho \le 1$ .
- Positive  $\rho$  means positive linear relationship between X and Y and vice versa for negative!
- The closer  $|\rho|$  is to 1, the stronger the relationship!

Presented by: Gerald Huang

## Part II: Sampling distributions and Central Limit Theorem

Presented by: Gerald Huang



### Independent and identically distributed random variables

A sequence of random variables  $X_1, X_2, \ldots, X_N$  are said to be *i.i.d* if

- **1** all  $X_i$ 's are independent.
- all X<sub>i</sub>'s share the same probability distribution (identically distributed).
  - In MATH2089/2859/2099/CVEN2002, we can assume that the random variables in a random sampling are *i.i.d.*

Presented by: Gerald Huang

# Central Limit Theorem (aka the Big Man of probability)

### What's this? Why do we care?

• CLT asserts:

For **any** random variable, the mean of a large random sample is approximately normal.

• Basically, regardless of its original distribution, the mean will *eventually* follow a normal distribution.



Presented by: Gerald Huang

## Standardising the CLT

### If we want to standardise the CLT...

### **Central Limit Theorem**

If  $X_1, X_2, \ldots, X_n$  is a random sample taken from a population with mean  $\mu$  and finite variance  $\sigma^2$  and if  $\overline{X}$  is the sample mean, then the limiting distribution of the standard mean follows the **standard** normal distribution. That is,

$$rac{ar{X}-\mu}{\sigma/\sqrt{n}}\stackrel{ extsf{a}}{\sim}\mathcal{N}(0,1).$$

• Note that  $\stackrel{a}{\sim}$  means "approximately follows" (as  $n \to \infty$ ).

Presented by: Gerald Huang

## **Estimators**

### **Definition: Estimators**

An **estimator** of  $\theta$  is a function of the sample

$$\hat{\Theta} = h(X_1, X_2, \ldots, X_n).$$

- An estimator is also a random variable!
- The most natural choice of our estimator is the sample mean! But we can have many other examples of estimators.

• 
$$\hat{\Theta}_1 = X_1.$$
  
•  $\hat{\Theta}_2 = \left(\frac{X_1 + X_n}{2}\right).$   
•  $\hat{\Theta}_3 = \left(\frac{2X_1 + X_n}{2}\right).$ 

Presented by: Gerald Huang

## **Properties of estimators**

### **Definition: Unbiased estimator**

An estimator  $\hat{\Theta}$  of  $\theta$  is said to be **unbiased** if and only if its mean is equal to  $\theta$ . That is

$$\mathbb{E}\left(\hat{\Theta}\right) = \theta.$$

• If an estimator is biased, then we can determine the bias by computing the difference

$$\mathsf{Bias}\left(\hat{\Theta}
ight) = \mathbb{E}\left(\hat{\Theta}
ight) - heta.$$

Presented by: Gerald Huang

### **Properties of estimators**

### Example: Biased vs unbiased estimators

$$\hat{\Theta}_1 = X_1$$
 is unbiased since  $\mathbb{E}(\hat{\Theta}_1) = \theta$ .  
But  $\mathbb{E}(\Theta_3) = \frac{1}{2} [2\mathbb{E}(X_1) + \mathbb{E}(X_n)] = \frac{3}{2}\theta$ . So  $\hat{\Theta}_3$  is biased.

Presented by: Gerald Huang

## **Properties of estimators**

### **Definition: Efficient estimator**

**Goal**: An unbiased estimator should have a smaller variance. Such an estimator is said to be *more efficient*.

### **Example: Efficiency of estimators**

$$Var(\Theta_1) = \sigma^2$$
 and  $Var(\Theta_2) = \frac{\sigma^2}{2}$ . Hence  $\Theta_2$  is more efficient than  $\Theta_1$ .

Presented by: Gerald Huang
## **Properties of estimators**

#### **Definition: Consistent estimator**

**Goal**: An unbiased estimator should also give better estimations as the number of samples grow larger. That is, an estimator is said to be *consistent* if

$$\operatorname{Var}\left(\hat{\Theta}
ight) o 0 \quad ext{as} \ n o \infty.$$

Presented by: Gerald Huang

## Combining all three properties of estimators

We can combine all three of these properties into a single formula that tells us how accurate an estimator is. This is the **mean squared error**, which can be evaluated by computing the following

$$\mathsf{MSE}\left(\hat{\boldsymbol{\Theta}}\right) = \mathsf{Var}\left(\hat{\boldsymbol{\Theta}}\right) + \mathsf{Bias}\left(\hat{\boldsymbol{\Theta}}\right)^2$$

A smaller MSE means a more accurate estimator.

Presented by: Gerald Huang

# Part III: Confidence intervals



40 / 72

 Basically... we want to find a suitable range for which our estimation misses the mark with probability  $\alpha$ . Note that  $\alpha$  is just a percentage here!

### **Definition: Confidence intervals**

A  $100(1-\alpha)$ % confidence interval for an unknown parameter  $\theta$  is a random interval [L, U], where L and U are statistics such that

 $\mathbb{P}(L \leq \theta \leq U) = 1 - \alpha.$ 

• Here, our random sample has a parameter of  $\theta$ !

## **Deriving confidence intervals**

- **①** Find a range of values that contains  $Z \sim \mathcal{N}(0, 1)$  with probability  $1-\alpha$ .
- 2 Apply the result of the CLT

$$rac{ar{X}-\mu}{\sigma/\sqrt{n}}\stackrel{\mathsf{a}}{\sim}\mathcal{N}(0,1).$$

Solve for  $\mu$  for which you have a  $100(1-\alpha)\%$  confidence interval for  $\mu$  to be

$$\left[\bar{x} - z_{1-\alpha/2}\frac{\sigma}{\sqrt{n}}, \bar{x} + z_{1-\alpha/2}\frac{\sigma}{\sqrt{n}}\right]$$

41 / 72

#### Remark

If the data is exactly normally distributed, then the confidence intervals are exact!

#### Remark

The length of the interval measures how precise estimation has been! The shorter, the more precise!

#### Remark

Confidence intervals don't have to be symmetric! In most cases, they aren't.

#### Example: (MATH2089, 2018 S2 Q3bi)

In August this year, Roy Morgan Research published a poll on Rugby viewership of New Zealanders. The poll, of 6,422 randomly selected New Zealanders, found that 43.6% of them watch Rugby on the television.

Find a 95% confidence interval for the true proportion of New Zealanders who watch Rugby on the television.

### Step 1.

Determine what the population proportion mean is.

$$\hat{p} = 0.436$$
 so  $1 - \hat{p} = 0.564$ .

So  $SE^2 = \frac{0.436 \times 0.564}{6422} = 0.00003829$ . So SE = 0.006187962. Hence the two sided confidence interval is

$$\left[ \bar{x} - z_{1-0.95/2} \times 0.006187962, \bar{x} + z_{1-0.95/2} \times 0.006187962 \right]$$

## Sample size determination

#### Margin of error

Given a pre-specified value *e* such that  $|\bar{x} - \mu| < e$ , the sample size determined is given by

$$e = z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}} \implies n = \left(\frac{z_{1-\alpha/2}\sigma}{e}\right)^2$$

Presented by: Gerald Huang

44 / 72

## Confidence interval for a proportion

• We made some inferences about the population mean  $\mu$  in the previous slides; let's move onto a population proportion  $\pi$ .

#### Sample proportion estimator

A useful estimator of the proportion is the sample proportion

$$\hat{P} = \frac{X}{n}$$

for some Binomial random variable X such that  $X \sim Bin(n, \pi)$ .

#### Sample proportion estimate

An estimate of 
$$\pi$$
 is simply  $\hat{p} = \frac{x}{n}$ 

## Sampling distribution of $\hat{P}$

Applying the Central Limit Theorem to  $\hat{P}$ , we obtain the result

$$rac{\hat{P}-\pi}{\sqrt{\pi(1-\pi)/n}}\stackrel{ extsf{a}}{\sim}\mathcal{N}(0,1).$$

Additionally, we can also say that

$$rac{\hat{P}-\pi}{\sqrt{\hat{P}(1-\hat{P})/n}}\stackrel{a}{\sim}\mathcal{N}(0,1).$$

## **Deriving confidence intervals**

- Find a range of values that contains  $Z \sim \mathcal{N}(0,1)$  with probability  $1-\alpha$ .
- 2 Apply the result of the CLT

$$rac{\hat{P}-\pi_0}{\sqrt{\pi(1-\pi)/n}}\stackrel{ extsf{a}}{\sim}\mathcal{N}(0,1).$$

Solve for  $\pi$  for which you have a  $100(1 - \alpha)\%$  confidence interval for  $\pi$  to be

$$\left[\hat{p}-z_{1-\alpha/2}\sqrt{\frac{\hat{p}(1-\hat{p})}{n}},\hat{p}+z_{1-\alpha/2}\sqrt{\frac{\hat{p}(1-\hat{p})}{n}}\right]$$

Presented by: Gerald Huang

## **One-sided confidence intervals**

We can also find one-sided large-sample confidence intervals for the proportion  $\pi$  by finding

$$\left[0, \hat{p} + z_{1-\alpha} \sqrt{\frac{\hat{p}(1-\hat{p})}{n}}\right] \quad \text{and} \quad \left[\hat{p} - z_{1-\alpha} \sqrt{\frac{\hat{p}(1-\hat{p})}{n}}, 1\right].$$

# Part IV: Hypothesis testing

Presented by: Gerald Huang

MATH2089/2859/2099/CVEN2002 Revision Seminar

49 / 72

# Before we begin... let's discuss an important distribution in statistics!

#### Student's *t*-distribution

A random variable T is said to follow a  $t_{\nu}$  distribution if for  $t \in \mathbb{R}$ ,

$$f(t) = \frac{\Gamma\left(\frac{\nu+1}{2}\right)}{\sqrt{\nu\pi}\Gamma\left(\frac{\nu}{2}\right)} \left(1 + \frac{t^2}{\nu}\right)^{-\frac{\nu+1}{2}}$$

for some integer  $\nu.$  Additionally,  $\Gamma$  is the gamma function.

•  $\nu$  is the **degrees of freedom** of the distribution!

#### Remark

As 
$$n \to \infty$$
,  $t_{\nu} \to \mathcal{N}(0, 1)$ .

Presented by: Gerald Huang

MATH2089/2859/2099/CVEN2002 Revision Seminar

50 / 72



#### (Part

## Null and alternative hypotheses

### (Definition) Null hypothesis

For the null hypothesis  $H_0$ , we claim that our population parameter takes some sort of value.

- It is a statement that we generally believe to be true.
- We say that  $H_0: \mu = \mu_0$ .

### (Definition) Alternative hypothesis

For the alternative hypothesis  $H_1$ , we have some sort of "new claim" that we want to test.

• We say that  $H_1: \mu \neq \mu_0$ .

Part

## Test statistic and null distribution

• To test  $H_0\mu = \mu_0$  using a random sample, when  $\sigma$  is known

$$Z = rac{(ar{X}-\mu_0)}{\sigma/\sqrt{n}} \stackrel{ extsf{a}}{\sim} \mathcal{N}(0,1).$$

• To test  $H_0: \mu = \mu_0$  using a normal random sample, when  $\sigma$  is not known:

$$T=rac{\hat{X}-\mu_0}{S/\sqrt{n}}\sim t_
u.$$

• To test  $H_0: \pi = \pi_0$  using a random sample

$$Z = \frac{\hat{P} - \pi_0}{\sqrt{\pi_0(1 - \pi_0)/n}} \stackrel{*}{\sim} \mathcal{N}(0, 1).$$

## **P-value**

### (Definition) *p*-values

The *P*-value is used to measure how much evidence there is **against**  $H_0$  in favour of the alternative hypothesis.

The smaller the p value, the more evidence against the null hypothesis there is. If there's enough evidence against  $H_0$ , we reject the null hypothesis.

Presented by: Gerald Huang



53 / 72

## Set up of hypothesis testing

- State the null and alternative hypotheses.
- 2 State the test statistic and distribution of  $H_0$ .
- Oraw a conclusion based on the corresponding *p*-value or rejection region.

Part

## Inferring conclusions

- At the end of the day, we want to determine whether the original claim *H*<sub>0</sub> was a lie or not. We can reach this using a **rejection region** for a statistic.
  - It is a range of values for which we would reject the null hypothesis at level  $\alpha.$

#### Hypothesis test about $\mu$ if $\sigma$ is known

• Test statistic: 
$$z = \frac{\bar{x} - \mu_0}{\sigma/\sqrt{n}}$$
  
• Rejection region  $(\mu > \mu_0)$ :  $\left\{ \bar{x} > \mu_0 + z_{1-\alpha} \frac{\sigma}{\sqrt{n}} \right\}$ .  
• Rejection region  $(\mu < \mu_0)$ :  $\left\{ \bar{x} < \mu_0 - z_{1-\alpha} \frac{\sigma}{\sqrt{n}} \right\}$ .  
• Rejection region  $(\mu \neq \mu_0)$ :  $\bar{x} \notin \left[ \mu_0 - z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}}, \mu_0 + z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}} \right]$ .

Presented by: Gerald Huang

#### Hypothesis test about $\mu$ if $\sigma$ is NOT known

• Test statistic: 
$$t = \frac{\bar{x} - \mu_0}{s/\sqrt{n}}$$

• Rejection region 
$$(\mu > \mu_0)$$
:  $\bar{x} > \mu_0 + t_{1-\alpha,n-1} \frac{s}{\sqrt{n}}$ .

• Rejection region 
$$(\mu < \mu_0)$$
:  $\bar{x} < \mu_0 - t_{1-\alpha,n-1} \frac{s}{\sqrt{n}}$ .

• Rejection region 
$$(\mu \neq \mu_0)$$
:  
 $\bar{x} \notin \left[ \mu_0 - t_{1-\alpha/2, n-1} \frac{s}{\sqrt{n}}, \mu_0 + t_{1-\alpha/2, n-1} \frac{s}{\sqrt{n}} \right]$ 

Presented by: Gerald Huang

MATH2089/2859/2099/CVEN2002 Revision Seminar

c

### Hypothesis test about $\pi$

• Test statistic: 
$$z = \frac{(\bar{p} - \pi_0)}{\sqrt{\pi_0(1 - \pi_0)/n}}$$

• Rejection region 
$$(\mu > \mu_0)$$
:  $\bar{p} > \pi_0 + z_{1-\alpha} \sqrt{\frac{\pi_0(1-\pi_0)}{n}}$ 

• Rejection region (
$$\mu < \mu_0$$
):  $\bar{p} < \pi_0 - z_{1-\alpha} \sqrt{\frac{\pi_0(1-\pi_0)}{n}}$ 

• Rejection region 
$$(\mu \neq \mu_0)$$
:  
 $\bar{x} \notin \left[ \pi_0 - z_{1-\alpha/2} \sqrt{\frac{\pi_0(1-\pi_0)}{n}}, \pi_0 + z_{1-\alpha/2} \sqrt{\frac{\pi_0(1-\pi_0)}{n}} \right].$ 

Presented by: Gerald Huang

MATH2089/2859/2099/CVEN2002 Revision Seminar

14

#### Example: (MATH2089, 2018S2 Q3c)

Assume Rugby New Zealand (the organising body for the sport) want to be able to demonstrate that Rugby viewership is in excess of 40% of New Zealanders, using a sample of size n. What are the appropriate null and alternative hypotheses for this test?

$$H_0: \pi = 0.4, \qquad H_a: \pi > 0.4.$$

Presented by: Gerald Huang

#### Example: (MATH2089, 2018S2 Q3c)

Assume Rugby New Zealand (the organising body for the sport) want to be able to demonstrate that Rugby viewership is in excess of 40% of New Zealanders, using a sample of size n. What is the distribution of the sample proportion  $\hat{p}$ , if the null hypothesis is true?

$$\mathcal{N}(0.4,\sqrt{0.4(1-0.4)/n}) = \mathcal{N}(0.4,0.4899/\sqrt{n}).$$

Presented by: Gerald Huang

Assume Rugby New Zealand (the organising body for the sport) want to be able to demonstrate that Rugby viewership is in excess of 40% of New Zealanders, using a sample of size n. Show that, for the relevant hypothesis test at the 0.05 significance level, the rejection region for  $\hat{p}$  can be expressed as

$$\left(0.4+rac{0.806}{\sqrt{n}},1
ight)$$

Rejection region is

$$\hat{p} > \pi_0 + z_{1-lpha} \sqrt{rac{\pi_0(1-\pi_0)}{n}} = 0.4 + z_{1-0.05} \sqrt{rac{0.4 imes 0.6}{n}}.$$
 This computes to

$$\hat{
ho} > 0.4 + 1.6449 imes 0.4899 / \sqrt{n} pprox 0.4 + 0.806 / \sqrt{n}.$$

Hence our rejection region is

$$\left(0.4 + \frac{0.806}{\sqrt{n}}, 1\right].$$

Presented by: Gerald Huang

MATH2089/2859/2099/CVEN2002 Revision Seminal

61 / 72

# Part V: Analyses

Presented by: Gerald Huang

MATH2089/2859/2099/CVEN2002 Revision Seminar

62 / 72

## Linear Regression

• Model the distribution of the random variable *Y*, conditional on the predictor *X*, assuming

$$Y = \beta_0 + \beta_1 x + \varepsilon.$$

The slope  $\beta_1$  and the intercept  $\beta_0$  are regression coefficients.

- $\beta_0$  is the **mean** of Y when X = 0.
- Slope  $\beta_1$  is the change in mean of Y when X increases by 1.

Presented by: Gerald Huang

## **Least Squares Estimators**

 We often don't know the true values of β<sub>0</sub> and β<sub>1</sub>. So the next best thing is to estimate them.



Presented by: Gerald Huang

## Assumptions based of the regression model

- Conditional mean is a linear function of x. Otherwise it doesn't make any sense!
- **2** Each error term  $e_i = y_i (\beta_0 + \beta_1 x_i)$  are drawn independently of one another!
- Sech error term have the same variance.
- Sech error term have been drawn from a normal distribution.

Presented by: Gerald Huang

## Inferences about the true slope

• 
$$\hat{\beta}_1 = \frac{S_{XY}}{S_{XX}} = \sum_i \frac{(x_i - \bar{x})}{S_{XX}} Y_i$$
, where  $Y \sim \mathcal{N}(\beta_0 + \beta_1 x_i, \sigma)$ .

• Sampling distribution of  $\hat{\beta}_1$  is

$$\hat{\beta}_1 \sim \mathcal{N}\left(\beta_1, \frac{\sigma}{\sqrt{S_{XX}}}\right).$$

• Apply a hypothesis test on  $\hat{\beta}_1$  with

$$H_0:\hat{\beta}_1=0, \qquad H_a:\hat{\beta}_1\neq 0.$$

• Reject  $H_0$  if  $\hat{\beta}_1$  is too different to 0. In other words, the rejection region is

$$\hat{\beta}_1 \notin \left[\hat{\beta}_1 - t_{n-2;1-\alpha/2}\frac{S}{\sqrt{S_{XX}}}, \hat{\beta}_1 + t_{n-2;1-\alpha/2}\frac{S}{\sqrt{S_{XX}}}\right]$$

MATH2089/2859/2099/CVEN2002 Revision Seminar

Presented by: Gerald Huang

## Inferences about $\beta_0$

• 
$$\hat{\beta}_0 = \sum_{i=1}^n \frac{Y_i}{n} - \hat{\beta}_1 \bar{x}.$$

• Sampling distribution of  $\hat{\beta}_1$  is

$$\hat{\beta}_0 \sim \mathcal{N}\left(\beta_0, \sigma \sqrt{\frac{1}{n} + \frac{\bar{x}^2}{S_{XX}}}\right).$$

Presented by: Gerald Huang

## Correlation

• Recall that a regression returns a numerical relationship between two random variables. On the other hand, a correlation quantifies the strength of the linear relationship between X and Y. We can show that the sample correlation coefficient is given by

$$r=\frac{S_{xy}}{\sqrt{S_{xx}S_{yy}}}.$$

Presented by: Gerald Huang

## Analysis of Variance (ANOVA)

• We use analysis of variance when dealing with *k* random samples, where  $\bar{X}_i$  and  $S_i$  are the sample mean and standard deviation of the *i*th sample.

**ANOVA model** 

$$X_{ij}=\mu_i+\varepsilon_{ij},$$

where  $\mu_i$  is the mean at the *i*th treatment and  $\varepsilon_{ij}$  is an individual random error component.

#### Assumptions

$$\varepsilon_{ij} \stackrel{\text{i.i.d}}{\sim} \mathcal{N}(\mathbf{0}, \sigma).$$

# • Errors are normally distributed, are independent and have the same variance.

Presented by: Gerald Huang

## **ANOVA** hypotheses

- Null hypothesis:  $H_0: \mu_1 = \mu_2 = \cdots = \mu_k$ .
- Alternative hypothesis:  $H_a$ : not all means are the same.
  - We're not saying that ALL means are different, but that at least two means are different.

## Fisher's *F*-distribution

Let  $f_{d_1,d_2;\alpha}$  be a value such that

$$\mathbb{P}(X > f_{d_1, d_2; \alpha}) = 1 - \alpha,$$

where X follows an  $F_{d_1,d_2}$  distribution with density

$$f(X) = \frac{\Gamma((d_1 + d_2)/2)(d_1/d_2)^{d_1/2}x^{d_1/2-1}}{\Gamma(d_1/2)\Gamma(d_2/2)((d_1/d_2)x + 1)^{(d_1+d_2)/2}}.$$

Yeah nah, I don't remember this at all! They would normally give you a value by computing the command finv( $\alpha$ , d1, d2) for quantiles and 1-fcdf(x,d1,d2).

Presented by: Gerald Huang

## **ANOVA** test

• Use the test statistic

$$f = \frac{\mathrm{ms}_{\mathrm{Tr}}}{\mathrm{ms}_{\mathrm{Er}}},$$

where f follows a Fisher distribution with  $d_1 = k - 1$  and  $d_2 = n - k$ .

• Reject  $H_0$  if

$$\frac{\mathsf{ms}_{\mathsf{Tr}}}{\mathsf{ms}_{\mathsf{Er}}} > f_{k-1,n-k;1-\alpha},$$

where  $\mathsf{ms}_{\mathsf{Tr}}$  is the treatment mean squared and  $\mathsf{ms}_{\mathsf{Er}}$  is the mean squared error.

Presented by: Gerald Huang